

An internet router receives data packets, and forwards them in the direction of their destination. When the line is busy, packets need to be queued.

Some data packets have **higher priority** than others, and need to be sent first. Queuing is not FIFO.

A **Priority Queue** is a **data type** where elements have different **priorities**. The priority queue provides three main methods:

**findMin** Return the **most urgent** element (**highest priority**, e.g. minimal event time).

**deleteMin** Remove the most urgent element from the priority queue.

**insert** Add a new element to the priority queue.

(an implementation of Priority Queues)

The abstract data type **Priority Queue** provides three main methods:

**findMin** Return the smallest element.

**deleteMin** Remove the smallest element.

**insert** Add a new element.

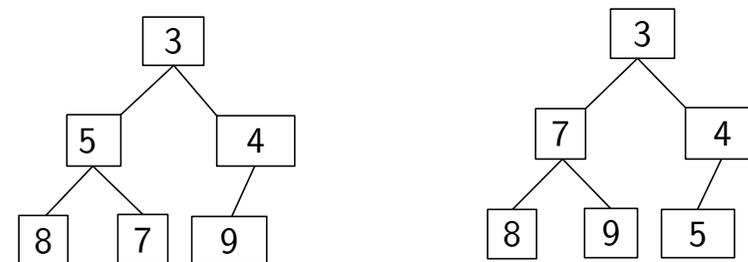
Implementation	<b>findMin</b>	<b>deleteMin</b>	<b>insert</b>
Unsorted list	$O(n)$	$O(n)$	$O(1)$
Sorted list	$O(1)$	$O(1)$	$O(n)$
Heap	$O(1)$	$O(\log n)$	$O(\log n)$

In `scala.collection.mutable.PriorityQueue[T]`, the methods are called `head`, `dequeue`, and `enqueue`.

```
scala> import scala.collection.mutable.PriorityQueue
scala> val p = new PriorityQueue[Double]
scala> p.enqueue(2.3, 5.9, 1.5, 9.8, 13.0)
scala> p.head
res1: Double = 13.0
scala> p.dequeue()
res2: Double = 13.0
scala> p.head
res3: Double = 9.8
scala> p.enqueue(11.2)
scala> p.head
res5: Double = 11.2
```

We will use a Heap: a **complete** binary tree, with one element per node.

**Heap-order:** For every node  $x$  with parent  $p$ , the element in  $p$  is smaller than the element in  $x$ .

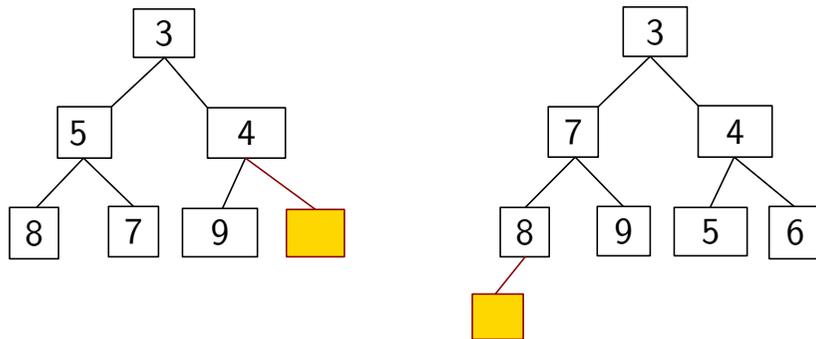


Many different heaps are possible for the same data.

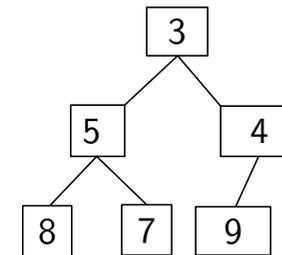
- The `insert` method adds a given element to the heap.
- We need to maintain heap order and completeness

There is only one correct node that can be added:

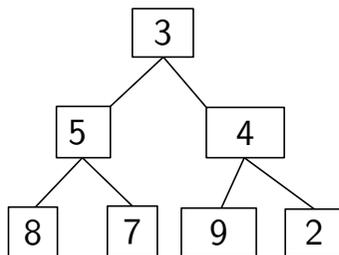
- Either the next open position from the left at level  $h$
- Or the first position in level  $h + 1$  if level  $h$  is full



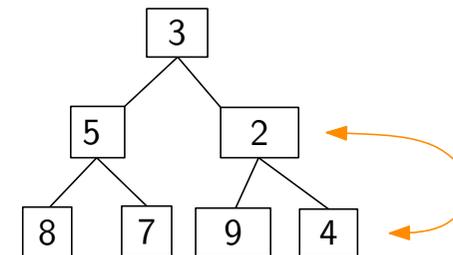
- Once we have placed the new node in the proper position, then we must account for the ordering property
- We simply compare the new node to its parent value and swap the values if necessary
- We continue this process up the tree until either the new value is greater than its parent or the new value becomes the root of the heap



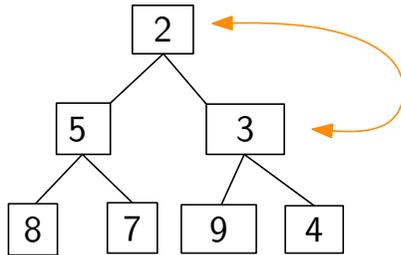
- Once we have placed the new node in the proper position, then we must account for the ordering property
- We simply compare the new node to its parent value and swap the values if necessary
- We continue this process up the tree until either the new value is greater than its parent or the new value becomes the root of the heap



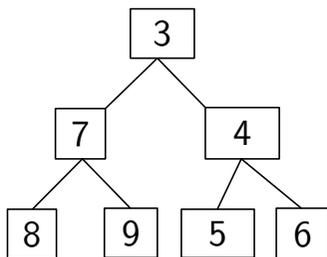
- Once we have placed the new node in the proper position, then we must account for the ordering property
- We simply compare the new node to its parent value and swap the values if necessary
- We continue this process up the tree until either the new value is greater than its parent or the new value becomes the root of the heap



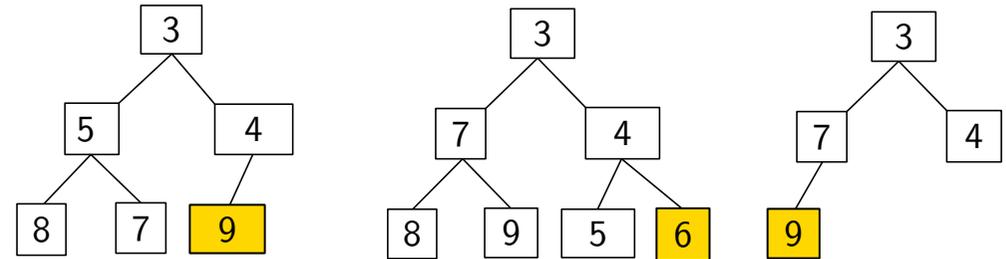
- Once we have placed the new node in the proper position, then we must account for the ordering property
- We simply compare the new node to its parent value and swap the values if necessary
- We continue this process up the tree until either the new value is greater than its parent or the new value becomes the root of the heap



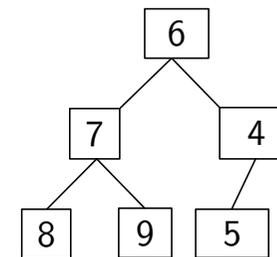
- Once the element stored in the last leaf has been moved to the root, the heap will have to be reordered
- This is accomplished by comparing the new root element to the smaller of its children and swapping them if necessary
- This process is repeated down the tree until the element is either in a leaf or is less than both of its children



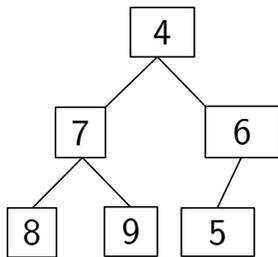
- The `deleteMin` method removes the minimum element from the heap
- The minimum element is always stored at the root
- After removing the minimum, we have to fill the root with a replacement element.
- The replacement element is always the last leaf
- The last leaf is always the last element at level h



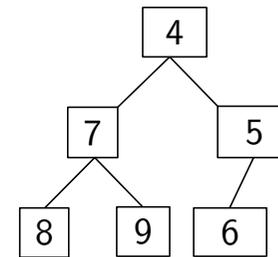
- Once the element stored in the last leaf has been moved to the root, the heap will have to be reordered
- This is accomplished by comparing the new root element to the smaller of its children and swapping them if necessary
- This process is repeated down the tree until the element is either in a leaf or is less than both of its children



- Once the element stored in the last leaf has been moved to the root, the heap will have to be reordered
- This is accomplished by comparing the new root element to the smaller of its children and swapping them if necessary
- This process is repeated down the tree until the element is either in a leaf or is less than both of its children



- Once the element stored in the last leaf has been moved to the root, the heap will have to be reordered
- This is accomplished by comparing the new root element to the smaller of its children and swapping them if necessary
- This process is repeated down the tree until the element is either in a leaf or is less than both of its children



Because the tree has a fixed structure, we can implement it using an array.

The height of the tree is  $\log n$ , and so `insert` and `deleteMin` take  $O(\log n)$  time.

Building a heap out of  $n$  given items takes time  $O(n \log n)$  using  $n$  insert operations.

We can do better: Just throw all  $n$  items into the array, then run `buildHeap` to fix the heap-ordering in  $O(n)$  time.

**Idea:** If we have a binary tree such that the two subtrees of the root are heaps, then we only need to let the root element percolate down into a correct position to ensure that the tree is a heap.

We can easily sort using a priority queue:

```

def pqSort(A: Array[E]) {
  val Q = new PriorityQueue[E]
  for (e1 <- A)
    Q.enqueue(e1)
  for (i <- 0 until A.length)
    A(i) = Q.dequeue()
}
  
```

What is the time-complexity?

- $n \times$  `insert`,
- $n \times$  `deleteMin`.

Priority queue implemented as unsorted list:

$n \times O(1)$  for `insert`:  $O(n)$

$n \times O(n)$  for `deleteMin`:  $O(n^2)$

$\approx$  Selection-Sort

Priority queue implemented as sorted list:

$n \times O(n)$  for `insert`:  $O(n^2)$

$n \times O(1)$  for `deleteMin`:  $O(n)$

$\approx$  Insertion-Sort

Priority queue implemented using binary heap:

$n \times O(\log n)$  for `insert`:  $O(n \log n)$

$n \times O(\log n)$  for `deleteMin`:  $O(n \log n)$

$\Rightarrow$  Heap-Sort

- Instead of inserting the  $n$  elements one by one, we create a heap operating on `A`;
- Use `buildHeap` to ensure heap ordering on the heap in  $O(n)$  time;
- Take out one element at a time using `deleteMin`.

We don't need extra storage!

We can put the items obtained by `deleteMin` into the array element that has become free because the size of the heap has decreased.

Improvements:

- Use max-heap so that items are sorted into increasing order
- Change indexing of array so that heap starts at index 0.