

Algorithm: A clearly specified set of instructions the computer will follow to solve a problem.

Given an algorithm, we want to determine the amount of memory it uses, and how much time it requires to solve a problem.

KAIST CS206 Maximum contiguous subsequence sum

Given an array with integers a_1, a_2, \dots, a_n , find the maximum value of $\sum_{k=i}^j a_k$.

4, -3, 5, -2, -1, 2, 6, -2

How many possible subsequences are there?

Algorism = process of doing arithmetic using Arabic numerals.

A misperception: algios [painful] + arithmos [number].

True origin: Abū 'Abdallāh Muhammad ibn Mūsā al-Khwārizmī was a 9th-century Persian mathematician, astronomer, and geographer, who wrote *Kitab al-jabr wa'l-muqabala* (Rules of restoring and equating), which evolved into today's high school mathematics text.



KAIST CS206

The naive algorithm

```

var maxSum = 0
for (i <- 0 until A.length) {
  for (j <- i until A.length) {
    var sum = 0
    for (k <- i to j)
      sum += A(k)
    if (sum > maxSum)
      maxSum = sum
  }
}

```

Number of additions: $\sum_{i=0}^{n-1} \sum_{j=i}^{n-1} (j - i + 1)$

```

var maxSum = 0
for (i <- 0 until A.length) {
  var sum = 0
  for (j <- i until A.length) {
    sum += A(j)
    if (sum > maxSum)
      maxSum = sum
  }
}

```

Number of additions: $\sum_{i=0}^{n-1} (n - i)$

- Split the problem into subproblems.
- Solve the subproblems recursively.
- Combine the solutions to the subproblems.

How can we apply recursion to this problem?

4, -3, 5, -2, -1, 2, 6, -2

Split the array in the middle.

- (1) The maximal subsequence is in the left half.
- (2) The maximal subsequence is in the right half.
- (3) The maximal subsequence begins in the left half and ends in the right half.

How many additions?

- Write a program implementing the algorithm
- Run the program with inputs of varying size and composition
- Use a method like `scala.compat.Platform.currentTimeMillis` to get an accurate measure of the actual running time

n	Naive	Faster	Recursive
10	2	1	1
100	760	31	19
1,000	652,285	2,411	236
10,000	–	218,210	2,378
100,000	–	23,033,000	25,037
1,000,000	–	–	260,375

Limitations:

- It is necessary to implement the algorithm, which may be difficult.
- Results may not be indicative of the running time on other inputs not included in the experiment.
- In order to compare two algorithms, the same hardware and software environments must be used. **Programming language, programming style, fine tuning** should not be measured.

While we do not know the exact cost of a primitive operation (it depends on the processor speed, processor architecture, programming language, compiler, etc.), we know that all primitive operations take **constant time**.

There is a fixed, finite number of primitive operations. Let a be the time taken by the fastest primitive operation, let b be the time taken by the slowest primitive operation. If our algorithm uses k primitive operations, then its running time $T(n)$ is bounded by

$$ak \leq T(n) \leq bk$$

- Uses a high-level description of the algorithm instead of an implementation
- Characterizes running time as a function of the input size n
- Takes into account all possible inputs, and looks at **worst-case**
- Allows us to evaluate the speed of an algorithm independent of the hardware/software environment

Theoretical analysis counts **primitive operations**.

Primitive operations are:

- Assigning a value to a variable
- Calling a method
- Arithmetic operations (e.g. adding two numbers)
- Indexing into an array
- Following a reference
- Returning from a method

We are more interested in the **growth rate** of the running time than in the exact formula. A quadratic algorithm will always be faster than a cubic algorithm if the input size is **sufficiently large**.

The growth rate determines the **scaling behavior** of an algorithm: If we increase the problem size by a factor 10, how much does the running time increase?

Or, put differently: If we buy a computer that is **ten times faster**, how much **larger problems** can we solve?

Time complexity	Problem size after speedup
n	$10s$
n^2	$3.16s$
n^3	$2.15s$
2^n	$s + 3.3$

Since we only want to know the growth rate of an algorithm, we can simplify the analysis using **Big-Oh notation**.

Definition of Big-Oh:

Let $f(n)$, $g(n)$ be functions from $\{1, 2, 3, 4, \dots\}$ to \mathbb{R} .

We say that $f(n)$ is $O(g(n))$ if there is a real constant $c > 0$ and an integer $n_0 \geq 1$ such that

$$f(n) \leq cg(n) \quad \text{for } n \geq n_0.$$

$4n + 1$ is $O(n)$

$2n^2 + 3n + 5$ is **not** $O(n)$

$2n^2 + 3n + 5$ is $O(n^2)$

The asymptotic analysis of an algorithm determines the running time in big- Oh notation.

To perform the asymptotic analysis

- We find the worst-case number of primitive operations executed as a function of the input size
- We express this function with big-Oh notation

Since constant factors and lower- order terms are eventually dropped anyhow, we can disregard them when counting primitive operations

A word of caution:

What is better, $10^{100}n$, n^{100} , or 2^n ?

We want to express the running time in the simplest possible Big-Oh notation.

$4n \log n + 3n - 12$ is $O(n \log n + 3n)$ is correct, but we should say that it is $O(n \log n)$.

Any polynomial

$$f(n) = a_0 + a_1n + a_2n^2 + a_3n^3 + \dots + a_dn^d$$

with $a_d > 0$ is just $O(n^d)$.

$5n^2 + 3n \log n + 2n + 5$ is $O(n^2)$

$20n^3 + 10n \log n + 5$ is $O(n^3)$

$3 \log n + 2$ is $O(\log n)$

2^{n+2} is $O(2^n)$

$2n + 100 \log n$ is $O(n)$

- Throughout the course of an analysis, keep in mind that you are interested only in significant differences in efficiency
- When choosing an ADT implementation, consider how frequently particular ADT operations occur in a given application
- Some seldom-used but critical operations must be efficient
- If the problem size is always small, you can probably ignore an algorithm's efficiency
- Weigh the trade-offs between an algorithm's time requirements and its memory requirements